H3-index Solution

efficient indexation





Problem Definition

• How can we determine if the issue reported by user W at coordinates (X, Y) pertains to organization Z?



Existing Solutions

Ray Casting Algorithm Definition

Input: A point (x, y) and a list of polygons, where each polygon is defined by a sequence of vertices $(x_1, y_1), (x_2, y_2), ..., (x \Box, y \Box)$.

Process:

For each polygon, check if the point lies inside it:

- 1. Imagine casting a horizontal ray from the point to the right (or any direction).
- 2. Count the number of times this ray intersects the edges of the polygon.
- 3. If the number of intersections is odd, the point is inside the polygon. If even, it's outside.

Edge Case Handling: Points exactly on an edge or vertex.

Can it scale up to **100 organizations**?

Simple Problem Statement:

- You have 100 polygons (regions). Not nested!
- Each polygon has 500 vertices, implying 500 edges
- You want to check which polygon contains a single given point (x, y).
- This requires iterating 100 * 500 = 50,000 times.

Certain optimizations can improve bounding box checks...

Problem

• Region indexation



Aveiro: **939 points** Universidade de Aveiro: **169 points**

(40.630451, -8.6551867) is inside which organization?

H3-Index Solution

Space filling - Contextualization

Solution: What about changing the indexation diagram?

- **Origin**: A geospatial indexing system created by Uber for optimized location-based solutions.
- **Structure**: Divides Earth's surface into a hierarchical grid of hexagons, from global to meter-level precision.
- **Purpose**: Enables efficient storage, retrieval, and analysis of spatial data across varying resolutions.
- **How It Works**: Assigns unique indexes to hexagons, supporting fast queries and scalable compression.
- **Applications**: Drives real-world solutions like ride pricing, fleet optimization, geographic analysis, and our specific use case.





Example: Space filling

Space filling - Hexagon Advantages

Solution: What about changing the indexation diagram?

- **Uniform Neighbor Distance**: Consistent spacing simplifies spatial analysis.
- **Circle-Like Shape**: Better for modeling nearest-neighbor queries.
- Efficient Tiling: Covers Earth with minimal distortion or gaps.
- Hierarchical Scale: Flexible resolution for data aggregation or detail.
- **Strong Adjacency**: Six neighbors enhance clustering and flow modeling.
- **Fast Indexing**: O(1) lookup speeds up localization area discovery.



All six neighbors of a hexagon (ring 1)



Our Solution

• Hierarchical Information



- Can we accept **nested** organizations? **Yes**
- Can we accept **multiple** organizations? **Yes**



H3 Index





(lat, lon) -> H3 cell

Average area in m²

Here are the same areas, but in m².

Res	Average <u>Hexagon</u> Area (m ²)	Pentagon Area* (m ²)
0	4,357,449,416,078.392	2,562,182,162,955.496
1	609,788,441,794.134	328,434,586,246.469
2	86,801,780,398.997	44,930,898,497.879
3	12,393,434,655.088	6,315,472,267.516
4	1,770,347,654.491	896,582,383.1 <mark>4</mark> 1
5	252,903,858.182	127,785,583.023
б	36,129,062.164	18,238,749.548
7	5,161,293.360	2,604,669.397
8	737,327.598	372,048.038
9	105,332.513	53,147.195
10	15,047.502	7,592.318



H3 Index Solution



Solution:

key: h-index
value: (organization, incident_id)

Problem Definition

User:

- user_id
- name
- email
- hash_password
- email_notification_flag

Operator:

- operator_id
- email
- hash_password
- organization_id

Organization:

- organization_id
- language
- region???

Incident:

- incident_id
- category
- main_description
- first_occurence_date
- centroid_location
- location???
- num_ocurrences
- severity
- status

Occurrence:

- occurrence_id
- photo_id
- photo_location???
- description
- date
- user_id
- incident_id

Architecture

